IN THE CLAIMS:

1. (Currently Amended) An actuator arm assembly for a disk drive, comprising:

a first stamped actuator arm, the first actuator arm including a first arm portion, a first

body portion defining a first body surface, the first stamped actuator arm further including a first

coil-supporting arm portion defining a first pair of coil supporting arms for supporting a coil of a

voice coil motor;

a second stamped actuator arm, the second stamped actuator arm including a second arm

portion, a second body portion defining a second body surface, the second stamped actuator arm

further including a second coil-supporting arm portion defining a second pair of coil supporting

arms for supporting the coil of the voice coil motor, the second pair of coll supporting arms

facing the first pair of coil supporting arms to define first and second coil attachment

surfaces, the first body surface facing the second body surface to define a third coil

attachment surface, and

a first layer of adhesive disposed between the first and second pairs of coil supporting

arms to attach the first and second actuator arms together.

wherein the first and second stamped actuator arms are configured such that when

the first stamped actuator arm is attached to the second stamped actuator arm,

the first pair of coil supporting arms faces and is in contact with the second

pair of coil supporting arms to define first and second coll attachment surfaces, and

the first body surface faces and is in contact with the second body surface to

define a third coil attachment surface.

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2. (Currently Amended) The actuator arm assembly of claim 1, wherein the first,

second and third coil attachment surfaces are configured to enable the coil to be is attached to

the actuator arm assembly by a first second layer of adhesive between the first coil attachment

surface and the coil, by a second third layer of adhesive between the second coil attachment

surface and the coil and by a third fourth layer of adhesive between the third coil attachment

surface and the coil.

3. (Currently Amended) The actuator arm assembly of claim 1, wherein the first

stamped actuator arm defines a first surface that defines a first through bore, the second stamped

actuator arm defines a second surface that defines a second through bore.

4. (Original) The actuator arm assembly of claim 3, further comprising a collar, the

collar being fitted within the first and second through bores.

5-10. (Canceled)

11. (Currently Amended) A disk drive, comprising:

a disk:

a head stack assembly for reading and writing to the disk, the head stack assembly

including an actuator arm assembly that comprises:

a first stamped actuator arm, the first actuator arm including a first arm portion, a first

body portion defining a first body surface, the first stamped actuator arm further including a first

coil-supporting arm portion defining a first pair of coil supporting arms for supporting a coil of a

voice coil motor;

a second stamped actuator arm, the second stamped actuator arm including a second arm

portion, a second body portion defining a second body surface, the second stamped actuator arm

further including a second coil-supporting arm portion defining a second pair of coil supporting

arms for supporting the coil of the voice coil motor, the second pair of coil supporting arms

facing the first pair of coil supporting arms to define first and second coil attachment

surfaces, the first body surface facing the second body surface to define a third coil

attachment surface, and

a first layer of adhesive disposed between the first and second pairs of coil supporting

arms to attach the first and second actuator arms together;

wherein the first and second stamped actuator arms are configured such that when

the first stamped actuator arm is attached to the second stamped actuator arm, the first pair

of coil supporting arms faces and is in contact with the second pair of coil supporting arms to

define first and second coil attachment surfaces, and the first body surface faces and is in

contact with the second body surface to define a third coll attachment surface;

a first head gimbal assembly coupled to the actuator arm assembly, and

a coil portion attached to the first, second and third coil attachment surfaces.

12. (Canceled)

13. (Currently Amended) The disk drive of claim 11, wherein the first, second and

third coil attachment surfaces are configured to enable the coil portion to be is attached to the

actuator arm assembly by a first second layer of adhesive between the first coil attachment surface

and the coil portion, by a second third layer of adhesive between the second coil attachment

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surface and the coil portion and by a third fourth layer of adhesive between the third coil

attachment surface and the coil portion.

14. (Currently Amended) The disk drive of elaim-5 claim 11, further including a

second head gimbal assembly coupled to the second actuator arm portion.

15. (Currently Amended) The disk drive of claim 5 claim 11, wherein the first

stamped actuator arm defines a first surface that defines a first through bore, the and the second

stamped actuator arm defines a second surface that defines a second through bore.

16. (Original) The disk drive of claim 15, further comprising a collar, the collar being

fitted within the first and second through bores.

17. (New) The actuator arm assembly of claim 1, further including a fifth layer of

adhesive disposed between the first and second body surfaces.

18. (New) The disk drive of claim 11, further including a sixth layer of adhesive

disposed between the first and second body surfaces.

19. (New) A method of manufacturing an actuator arm assembly, comprising:

a first providing step to provide a first stamped actuator arm, the first actuator arm

including a first arm portion, a first body portion defining a first body surface, the first stamped

actuator arm further including a first coil-supporting arm portion defining a first pair of coil

supporting arms for supporting a coil of a voice coil motor;

a second providing step to provide a second stamped actuator arm, the second stamped

actuator arm including a second arm portion, a second body portion defining a second body

surface, the second stamped actuator arm further including a second coil-supporting arm portion

defining a second pair of coil supporting arms for supporting the coil of the voice coil motor, and

a first bonding step to bond the first and second pairs of coil supporting arms together to

define first and second coil attachment surfaces.

20. (New) The method of claim 19, wherein the first bonding step includes a step of

applying a first layer of adhesive between the first and second pairs of coil supporting arms.

21. (New) The method of claim 19, wherein the first bonding step includes a first

welding step to weld the first and second pairs of coil supporting arms together.

22. (New) The method of claim 19, further comprising a second bonding step to bond

the first body surface to the second body surface to define a third coil attachment surface.

23. (New) The method of claim 22, wherein the second bonding step includes a step of

applying a second layer of adhesive between the first and second body surfaces.

24. (New) The method of claim 22, wherein the second bonding step includes a second

welding step to weld the first and second body surfaces together.

25. (New) The method of claim 19, wherein the first providing step includes a step of

stamping the first actuator arm from a first sheet of flat material.

26. (New) The method of claim 19, wherein the second providing step includes a step

of stamping the second actuator arm from a second sheet of flat material.